



Distribution System Analysis

Panel Session – Induction Machine Modeling

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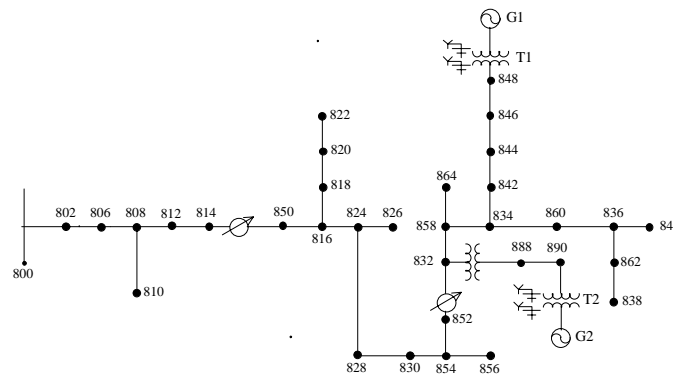


Agenda

1. Introduction
2. System Modeling
3. Power Flow Validation
4. Wind Generator Modeling
5. Slip and Power Flow Results
6. Short-Circuit Analysis
7. Conclusions

Introduction

1. IEEE 34-Bus Test Feeder



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Key points:

- PSCAD Model was built of the IEEE 34 Bus test system.
- Model include all transformers, regulators plus controls, induction generators, loads, distribution lines, and wind turbines.
- Model power flows are validated against the benchmarks.
- The case was solved in 114s for a 6s run using a time step of 250us (no induction machines). The same case with induction machines solved in 181s.



Distribution System Modeling

1. Unbalanced Distribution Line
2. Distributed loads
3. Phase load (constant pq , Z , and I)
4. Phase to Phase load
5. Regulators and controls

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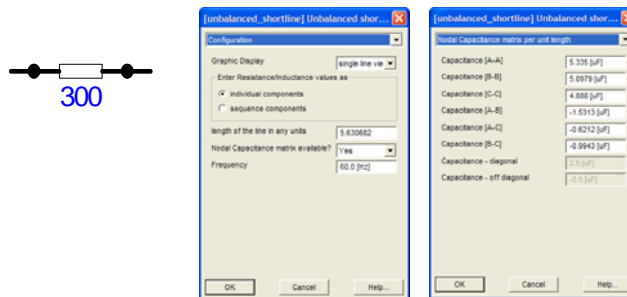
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Key points:

- The first test case included these elements to validate against a power flow.
- Subsequent slides document what was done for each element.

1. Unbalanced Distribution Line

- A mutually coupled wires are used
- Z & B matrices are directly entered



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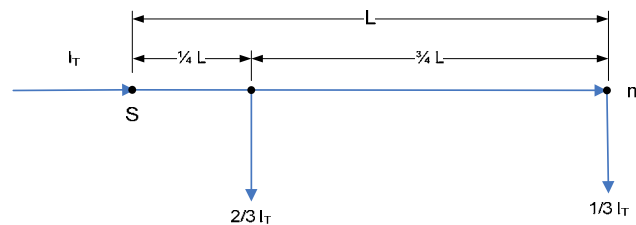
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Key points:

- Each type of standard construction was modeled. Six types of construction models included 300, 301, 302, 303, 304 and 305.
- Specification of Susceptance (B) values precluded use of standard models, thus a new component was created to address the tightly coupled unbalanced distribution line.
- The lack of long transmission lines enforces a large and tightly couple matrix in this analysis. This makes it difficult for an efficient solution in the time domain when transmission line boundaries can not be used to form subsystems.

2. Distributed loads

- One-third of the load is placed at the end of line
- Two-thirds of the load be placed one-fourth of the way from the source end



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Key points:

- Distributed load was modeled as above. This is based on a reference (Get from Surya)
- Load is connected at the interface points to match its unbalance requirements.

3. Phase load (constant pq, Z, and I)

- Constant power

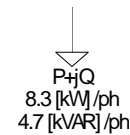
- $N_p = N_q = 0$
- $K_{pf} = K_{qf} = 0$

- Constant Z

- $N_p = N_q = 2$
- $K_{pf} = K_{qf} = 0$

- Constant Current:

- $N_p = N_q = 1$
- $K_{pf} = K_{qf} = 0$



$$P = P_0 \cdot \left(\frac{V}{V_0} \right)^{N_P} \cdot (1 + K_{PF} \cdot dF)$$

$$Q = Q_0 \cdot \left(\frac{V}{V_0} \right)^{N_Q} \cdot (1 + K_{QF} \cdot dF)$$

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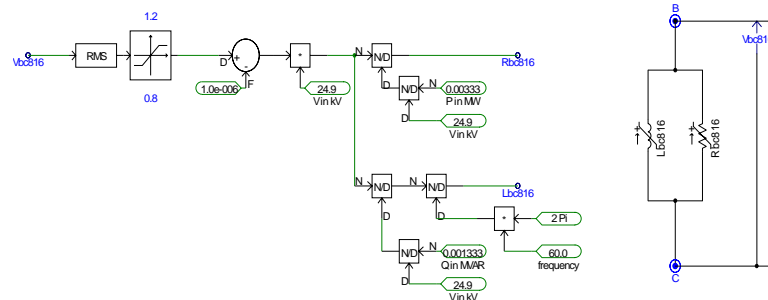
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Key points:

- A standard PSCAD model was used for phase to ground loads, formulas is widely used in industry
- Constant PQ, constant impedance, constant current is modeled depending on the parameters entered.
- Frequency variability in the load is not considered.

4. Phase to Phase load

- The phase to phase load is represented by a variable resistor and inductor whose values are updated at every time-step.



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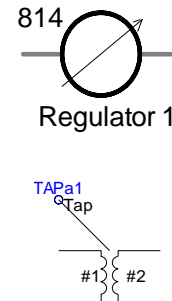
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Key points:

- Phase to phase load modelled as R//L circuit adjusted with voltage every time step.
- More research work is required accurate load modeling in a time domain algorithm.

5. Regulators and controls

- 1-Phase 2-Winding Transformer with online tap changer
- Regulator controls include
 - Set voltage
 - Initial tap setting
 - Bandwidth
 - Out-of-band detector
 - Control time delay
 - Tap position calculator
 - Timer reset
 - Line compensation



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Key points:

- A regulator model needed to be built to accommodate the IEEE benchmark case
- Standard single phase transformers were used with very low leakage reactance and zero losses. No information was available on this but this can easily be added in PSCAD.
- Regulator control built to model a realistic regulator control with V setting, R, X, BW, Timer reset and Time delays.
- Regulators sequenced in time similar to a real regulator voltage control application.

PSCAD Power Flow Results

Node Voltage pu			
Node	A-N	B-N	C-N
800	1.05	1.05	1.05
802	1.047	1.048	1.048
806	1.046	1.047	1.047
808	1.014	1.03	1.029
810		1.029	
812	0.9769	1.01	1.006
814	0.9474	0.9943	0.9887
850	1.018	1.025	1.02
816	1.018	1.025	1.019
818	1.017		
820	0.9941		
822	0.9912		
824	1.009	1.016	1.011
826	1.016		
828	1.008	1.015	1.01
830	0.9903	0.998	0.9929
854	0.9898	0.9976	0.9925
852	0.9589	0.9678	0.9627
832	1.037	1.034	1.035
858	1.034	1.032	1.033
834	1.032	1.029	1.03

Power Flow kW/kVR						
Node	P A	Q A	P B	Q B	P C	Q C
800	757.9	174.1	666.2	87.94	620.5	31.02
802	756.3	169	665.2	87.8	619.6	31.04
806	755.2	168.8	633.3	75.46	593.3	14.78
808 to 812	735.1	164.5	606.4	64.44	582.3	18.32
808 to 810			16.63	7.218		
810			0	0		
812	711.6	158.8	595.4	62.79	569.4	18.06
814	692.8	150.5	586.7	61.8	559.1	17.45
850	692.8	150.5	586.7	61.8	559.1	17.45
816 to 824	521.7	75.86	586.5	61.79	559	17.44
816 to 818	170.8	76.62				
818	170.7	77.63				
820	132.8	66.52				
822	0	0				
824 to 828	517.5	75.27	537.6	39.81	552.3	13.9
824 to 826			40.46	19.38		
826	0	0				
828	517.1	78.47	537.3	39.79	548	10.35
830	486.4	61.3	518.3	38.37	520	9.81
854 to 852	486.2	64.46	514.2	38.08	519.8	9.81
854 to 856			3.887	-1.915		
852	472.4	65.68	498.9	40.1	503.9	6.34
832 to 858	319.6	-20	345.8	-44.1	353.6	-76.7
832 to 888	152.8	85.24	153.1	82.91	150.3	82.14
858 to 834	310	-21.43	340.6	-47.8	347.8	-75.5
858 to 864	2.056	0.739				
834 to 842	174.7	-133.3	211.6	-116.2	183.5	-126.9
834 to 860	127.5	106.5	116.6	67.19	149.6	45.59

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Key points:

-PSCAD model validated against published results with small errors. See error slide for comparison.

PSCAD Power Flow Results

Node Voltage pu			
Node	A-N	B-N	C-N
842	1.032	1.029	1.03
844	1.031	1.029	1.03
846	1.032	1.029	1.03
848	1.032	1.029	1.03
860	1.031	1.029	1.03
836	1.031	1.028	1.03
840	1.031	1.029	1.03
862	1.031	1.029	1.03
838		1.028	
864	1.034		
888	0.9961	1.004	0.9962
890	0.9134	0.9294	0.9138
856		0.9976	

Power Flow kW/kVR						
Node	P A	Q A	P B	Q B	P C	Q C
842	174.7	-133.3	211.6	-116.2	183.4	-126.9
844	20.66	-144.5	68.28	-120.8	40.81	-132.8
846	20.66	-143.5	42.34	-132.3	20.57	-143.7
848	20.45	-143.4	19.35	-142.9	20.75	-143
860	55.29	28.12	76.31	44.05	47.7	23.23
836 to 840	21.31	6.48	30.6	15.91	17.13	19.29
836 to 862			28.07	12.88		
840	9.34	7.295	9.29	7.139	9.192	7.182
862			28.06	13.07		
838			0	0		
864	0	0				
888	147.8	76.53	151.4	77.8	147.3	77.07
890	136.8	69.55	140.8	69.56	135.6	68.3
856			0	0		

Voltage Regulator				
Node 814			Node 852	
Phase	IEEE	PSCAD	IEEE	PSCAD
A	12	13	13	13
B	5	5	11	13
C	5	5	12	13

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Key points:

- PSCAD results are very close
- Largest real power error <1% without machines.

Errors

Node Voltage %			
Node	A-N	B-N	C-N
800	0.00%	0.00%	0.00%
802	-0.05%	-0.04%	-0.04%
806	0.03%	-0.04%	-0.04%
808	0.04%	0.04%	-0.06%
810		-0.04%	
812	0.06%	0.00%	-0.09%
814	0.07%	-0.02%	-0.06%
850	0.04%	-0.05%	-0.03%
816	0.08%	-0.05%	-0.10%
818	0.07%		
820	0.15%		
822	0.17%		
824	0.08%	0.02%	-0.06%

826		0.04%	
828	0.06%	-0.01%	-0.09%
830	0.09%	-0.02%	-0.09%
854	0.08%	-0.02%	-0.09%
852	0.08%	-0.02%	-0.10%
832	0.11%	-0.05%	-0.10%
858	0.04%	-0.02%	-0.08%
834	0.11%	-0.05%	-0.13%

842	0.11%	-0.04%	-0.13%
844	0.03%	-0.01%	-0.11%
846	0.11%	-0.01%	-0.13%
848	0.10%	-0.01%	-0.14%
860	0.05%	-0.01%	-0.10%
836	0.07%	-0.07%	-0.08%
840	0.07%	0.03%	-0.08%
862	0.07%	0.03%	-0.08%
838		-0.05%	
864	0.04%		
888	-0.36%	0.57%	-0.38%
890	-1.37%	0.03%	0.07%
856		-0.01%	

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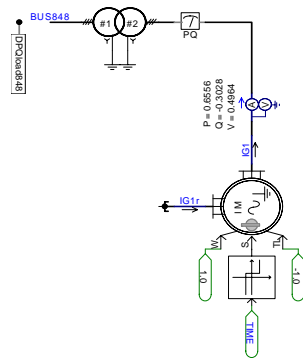
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Excellent agreement in load flow, generally much less than 0.2%

Wind Generators

Two induction generators added at buses 848 and 890 to Represent 660 kW wind turbine generators.



- Results agree with steady state calculations.

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Key points:

-Squirrel cage induction motors modeled using wound rotor model. Rotor currents are monitored for additional analysis.

Wind Generators

Two induction generators added at buses 848 and 890 to Represent 660 kW wind turbine generators.

- Results agree with steady state calculations.

Slip			
Node 848		Node 890	
IEEE	PSCAD	IEEE	PSCAD
-0.00751	-0.0073	-0.00912	-0.0087

Voltage Regulator				
Node 848			Node 890	
Phase	IEEE	PSCAD	IEEE	PSCAD
A	6	8	6	5
B	1	1	6	6
C	0	2	5	6

Reactive Power (KVar)	
Node 848	Node 890
312	316

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Key points:

- PSCAD modeled generator slip agree very closely in steady state.
- Slip error is 2.7%, 4.6% are small.
- Regulator tap position differ slightly in this solved case. This can be due to the differences in dead band control of the regulator, and distributed load modelling differences.

Wind Generators

- Results agree with steady state calculations.

Generator Node Voltage (V)			
Node 848		Node 890	
IEEE	PSCAD	IEEE	PSCAD
282	284	259	262
281	285	258	265
282	285	260	263

	Generator currents (A)			
	Node 848		Node 890	
	IEEE	PSCAD	IEEE	PSCAD
Positive seq	871	855	953	925
Negative Seq.	21	12	22	13

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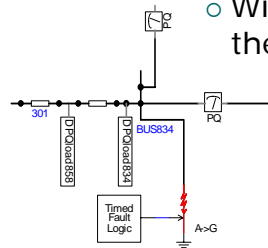
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Key points:

-Error percentages on the generator pos seq currents < 2.9%

Wind Generators

- Fault on Bus 834
 - A-G Fault (not cleared)
 - A number of factors are important
 - Machine inertia
 - Wind turbine characteristic will determine the input torque variation.

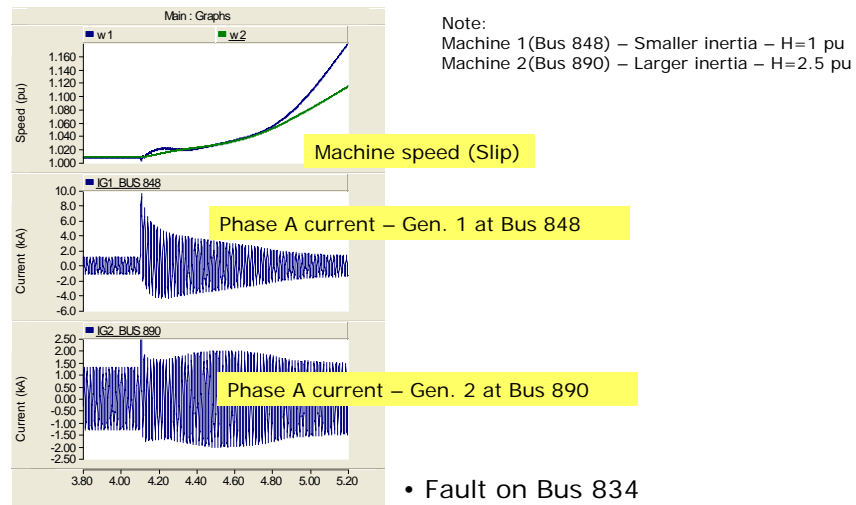


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Wind Generators



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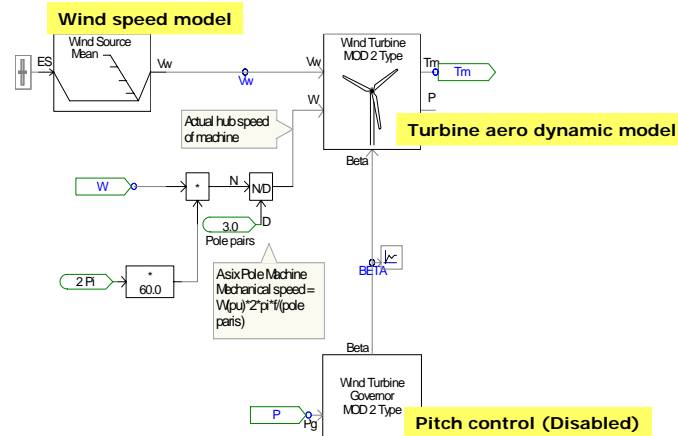
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Key points:

- Fault is applied, generator currents vary widely as the fault develops
- Machine speed is dependent on machine inertia (data was not provided so two typical values were assumed $H=1$, and $H=2.5$)
- Machine response assume constant Torque, this may not be realistic depending on the machine.

Wind Turbine Model



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Key points:

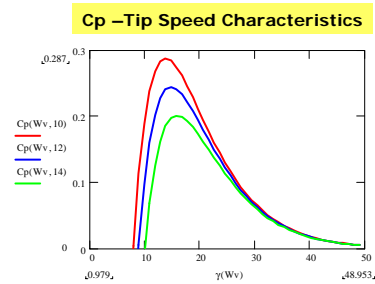
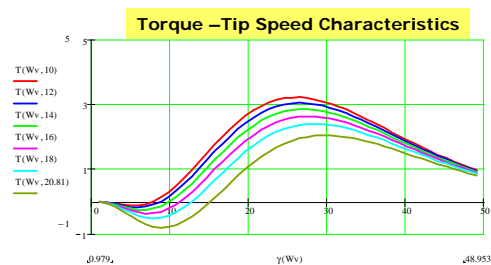
- Wind turbine model is pitch stall control
- Based on work done by PhD candidate Rhonda Peters at University of North Dakota and Dr. Muthumuni (HVDC Research Centre)
- Pitch control is disabled. Represents a simple wind turbine.

Wind Turbine Model

$$P(W_v, \beta) := \frac{1}{2} \cdot \rho \cdot A \cdot W_v^3 \cdot C_p(W_v, \beta)$$

$$\text{Tip_Speed} := \frac{\text{Wind_Speed}}{\text{Hub_Speed}}$$

In stall control the pitch angle is not changed.



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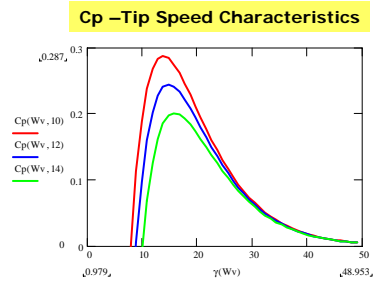
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Key points:

- As the machine speeds up during the fault, tip speed ratio decreases. This changes T_m .
- Simulation is set up at 20 m/s wind speed, providing a 20.81 constant beta.
- C_p is dependent on Tip Speed Ratio.

Wind Turbine Model

- In stall control the pitch angle is not changed.
- Blades designed to have a sharp drop in C_p at wind speed above a design limit (Turbulence effects)

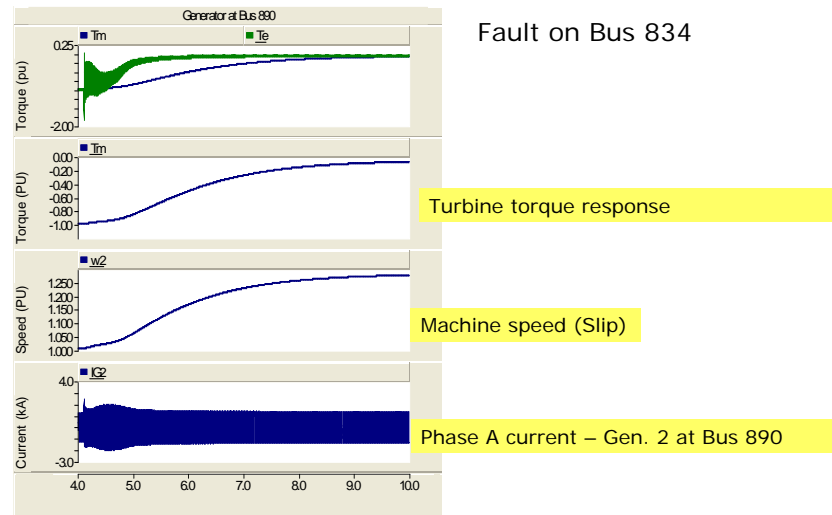


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Wind Generators



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Key points:

-Negative torque : due to sign convention



Conclusions

- IEEE 34 bus distribution network is completely modeled in a transient program.
- New models were developed as a result of this effort to meet the challenging needs of the distribution engineer.
- Power, Reactive Power, Voltage, and tap changer results are validated against steady state calculations provided in the test case document.
- Two induction generators were added to the original model and the steady state results were validated.
- Function of the voltage regulators validated.
- The response of the machine during a system fault was analyzed.
 - Wind turbine characteristics will impact those results.
 - Initial transients and dc offsets in the fault current can be studied.

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Additional Points:

- The test case can be made available from the PSCAD.COM Forum.
- This presentation will be made available on the same Forum for general distribution.